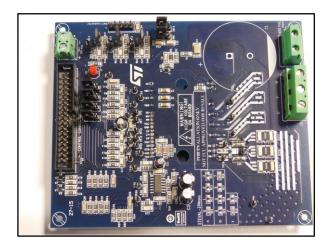


## STEVAL-IPM07F

# Motor control power board based on the SLLIMM™ 2nd series of IGBT IPMs

Data brief



#### **Features**

- Input voltage: 125 400 V<sub>DC</sub>
- Nominal power: up to 800 W
- Input auxiliary voltage: up to 20 V DC
- Single or three-shunt resistors for current sensing (with sensing network)
- Two options for current sensing: dedicated op-amps or through MCU
- Overcurrent hardware protection
- IPM temperature monitoring and protection
- Hall sensor or encoder input
- Uses the STGIF7CH60TS-L IGBT intelligent power module from the SLLIMM™ 2<sup>nd</sup> series IPMs
- Motor control connector (32-pin) interfacing with ST MCU boards
- Universal conception for further evaluation with bread board and testing pins
- Very compact size

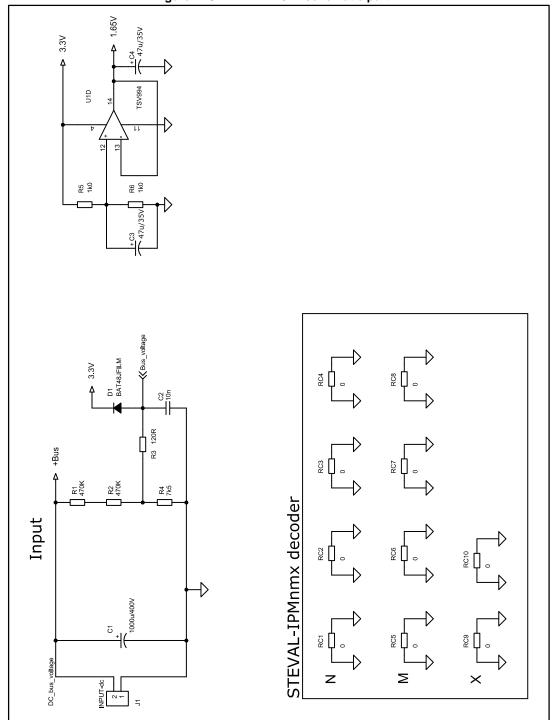
### **Description**

The STEVAL-IPM07F is a compact motor drive power board based on the small low-loss intelligent molded module SLLIMM™ 2<sup>nd</sup> series product (STGIF7CH60TS-L). It provides an affordable and easy-to-use solution for driving high power motors for a wide range of applications such as power white goods, air conditioning, compressors, power fans, high-end power tools and 3-phase inverters for motor drives in general. The IPM itself consists of shortcircuit rugged IGBTs and a wide range of features like undervoltage lockout, smart shutdown, internal temperature sensor and NTC, and overcurrent protection. The main characteristics of this evaluation board are small size, minimal BOM and high efficiency. It includes an interface circuit (BUS and Vcc connectors). bootstrap capacitors, snubber capacitor, hardware short-circuit protection, fault event signaling and temperature monitoring. In order to increase the flexibility, it is designed to work in single- or three-shunt configurations and with two current sensing options: either three dedicated onboard op-amps or with op-amps embedded on the MCU. The Hall/Encoder part completes the circuit. Thanks to these advanced characteristics, the system is able to achieve fast and accurate current feedback conditioning, meeting most of the requirements for field oriented control (FOC). The STEVAL-IPM07F is compatible with ST's STM32-based control board, for a complete motor control platform.

Schematics STEVAL-IPM07F

# 1 Schematics

Figure 1: STEVAL-IPM07F schematic part 1



STEVAL-IPM07F Schematics

phase\_C phase\_B phase\_A SW3 Motor Output e α ← Bus\_voltage M\_phase\_C ₹3.30 Control Connector NTC\_bypass\_relay >> M\_phase\_B >> EM\_STOP PWM-A-H PWM-A-L PWM-B-H PWM-B-L PWM-C-H PWM-C-H PWM\_Vref X M\_phase\_A Current\_C Current\_A  $\frac{\omega}{Q}$  SW1 ω SW4 Current\_B E3分 Current\_A\_amp Current\_C\_amp 

✓  $\frac{\omega}{2}$  SW2 Current\_B\_amp

Figure 2: STEVAL-IPM07F schematic part 2

GSPG06112015DI1535

Schematics STEVAL-IPM07F

TSV994 U1C R39 2K1 R34 2K1 <del>1</del>6 R35 R37 Ş3 3.3V R31 R41 TSV994 N1A 15 <del>1</del> U1B R29 2k1 R43 2K1 R33 2K1 R38 2k1 100 T R42 1.65∨ 4 R30 R32

Figure 3: STEVAL-IPM07F schematic part 3

STEVAL-IPM07F Schematics

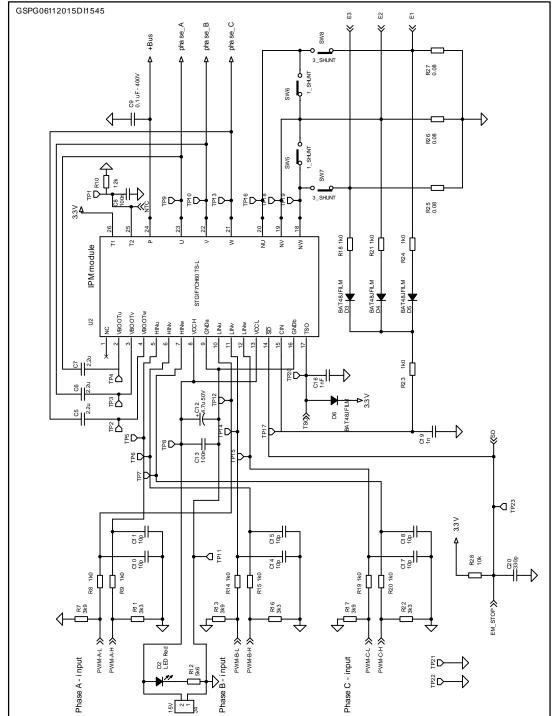


Figure 4: STEVAL-IPM07F schematic part 4

Schematics STEVAL-IPM07F

GSPG06112015DI1550 M phase B M\_phase\_C SW15 R52 4k7 SW14 R51 4K7 SW13 R50 4k7 R46 4k7 C37 10p R45 4k7 C36 10p Hall / Encoder R44 4K7 C35 10p 0 ½ 2k4 2k4 SW12 SW11 R48 R47 100n က<mark>ြ</mark> SW16 e Sw<sub>θ</sub> Encoder/Hall 1 0 0 4 c H1/A+ H2/B+ H3/Z+ + 3.3/5V GND +5∨4 3.3∨ 4

Figure 5: STEVAL-IPM07F schematic part 5

STEVAL-IPM07F Revision history

## 2 Revision history

**Table 1: Document revision history** 

Date	Version	Changes
12-Nov-2015	1	Initial release.
16-Mar-2016	2	Updated Figure 1: "STEVAL-IPM07F schematic part 1" and Figure 3: "STEVAL-IPM07F schematic part 3"

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